

## ABSTRACT OF THE DISCLOSURE

In a remote controlled robotic manipulator 20 a motion sensor 26 senses motion of a region of an object to be manipulated. A controller 50 locks motion of the robotic manipulator 26 relative to the region of the object and also selects the region of the  
5 object to be sensed. As a result the frame of reference of the manipulator is locked to the relevant region of the object to be manipulated improving ease of control and manipulation.